



# Doppler Shift Based Opportunistic LEO-PNT With Starlink Signals

Winfried Stock

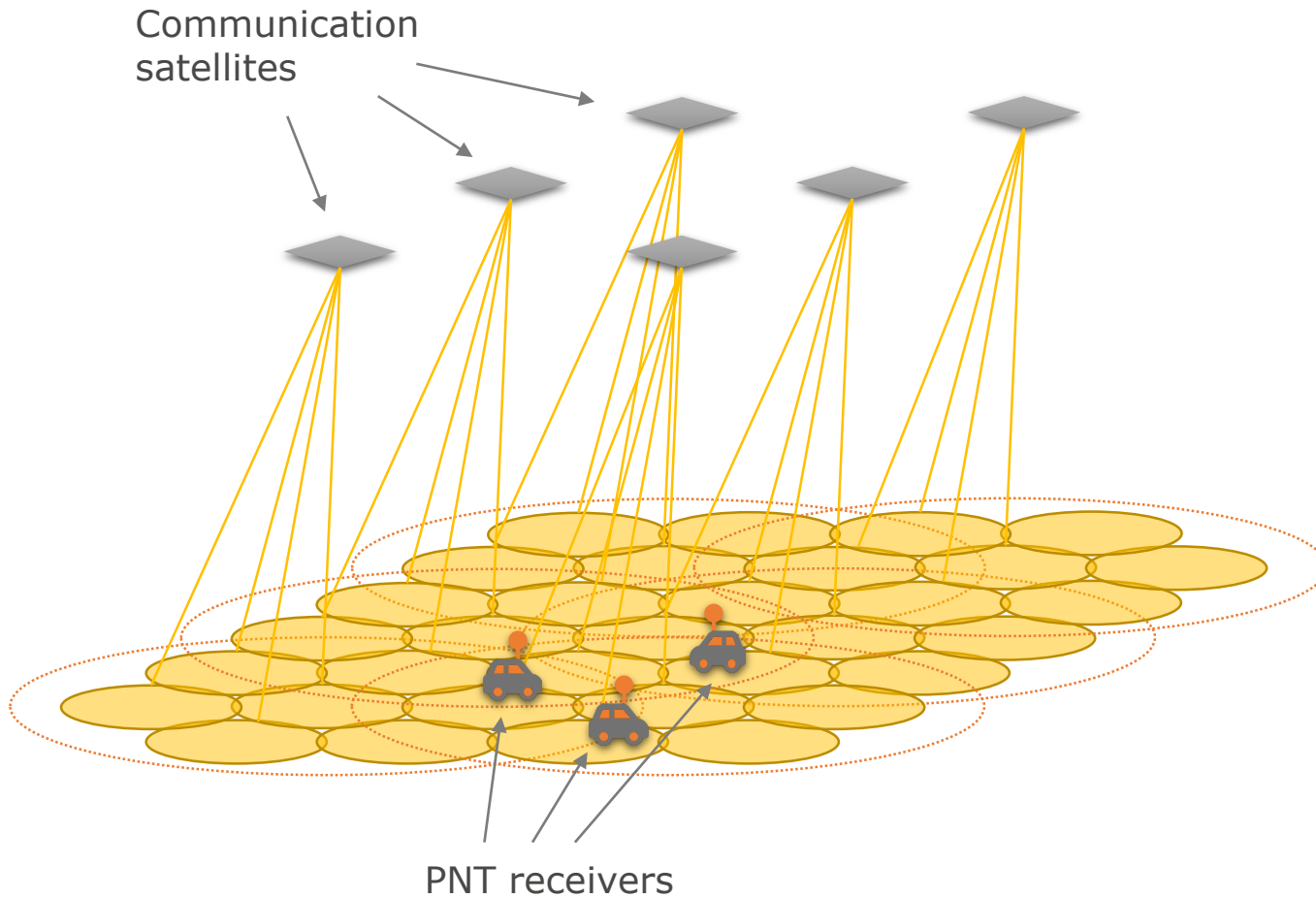
IEEE LEO Sats Workshop: LEO Position, Navigating, and Timing (PNT)  
5 May 2025



**Munich Center for  
Space Communications**



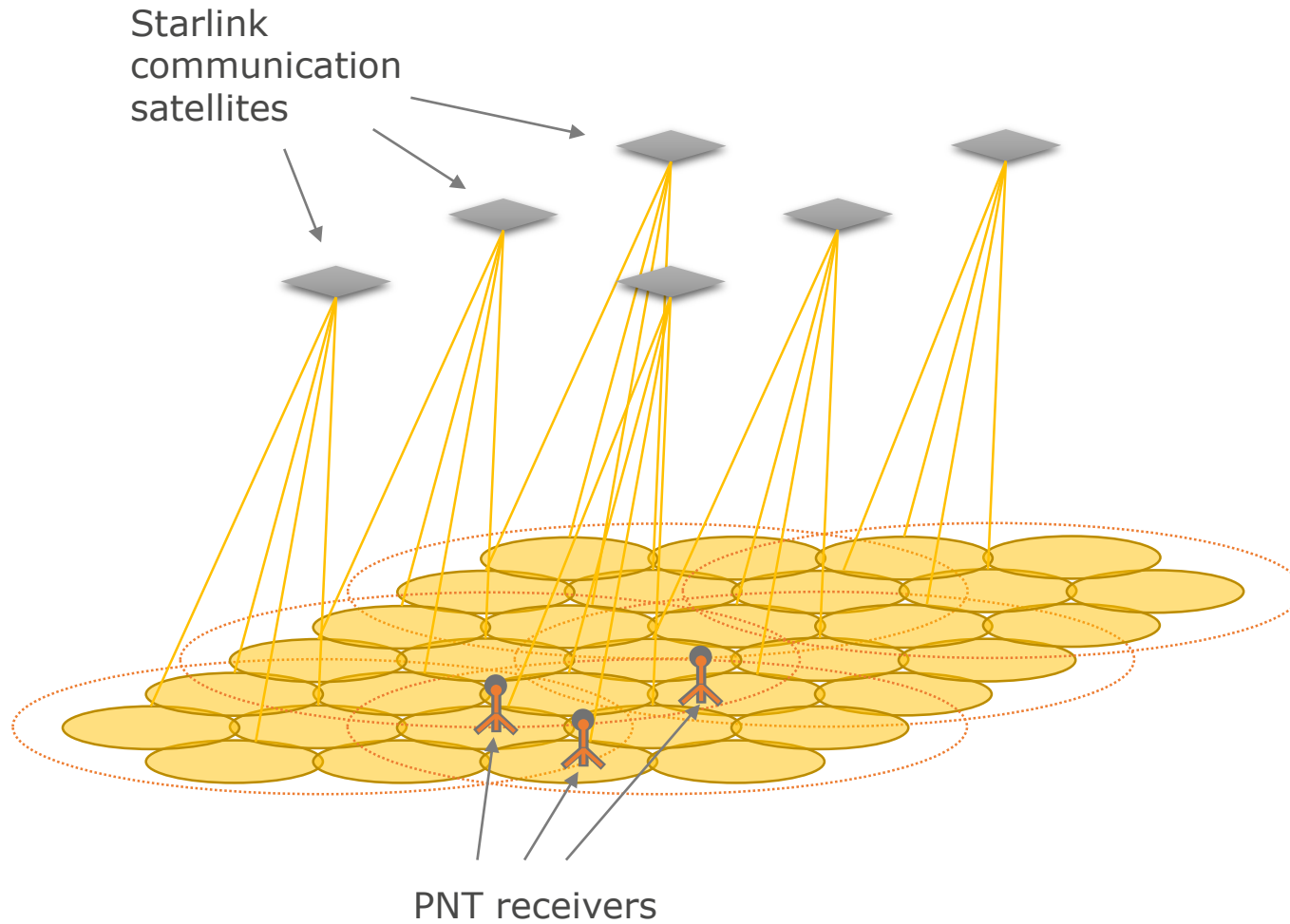
**Chair of  
Signal Processing**  
*Univ.-Prof. Dr.-Ing. Andreas Knopp*



- (Unmodified) LEO satellites transmit communication signals
- PNT estimation at the receiver based on
  - Observation of the communication signals (as „signals of opportunity“)
  - Satellite orbit
- ✓ No additional (PNT) satellites required
- ✓ Approach for complementary PNT in case of interruption or degradation of GNSS
- ✓ Global coverage

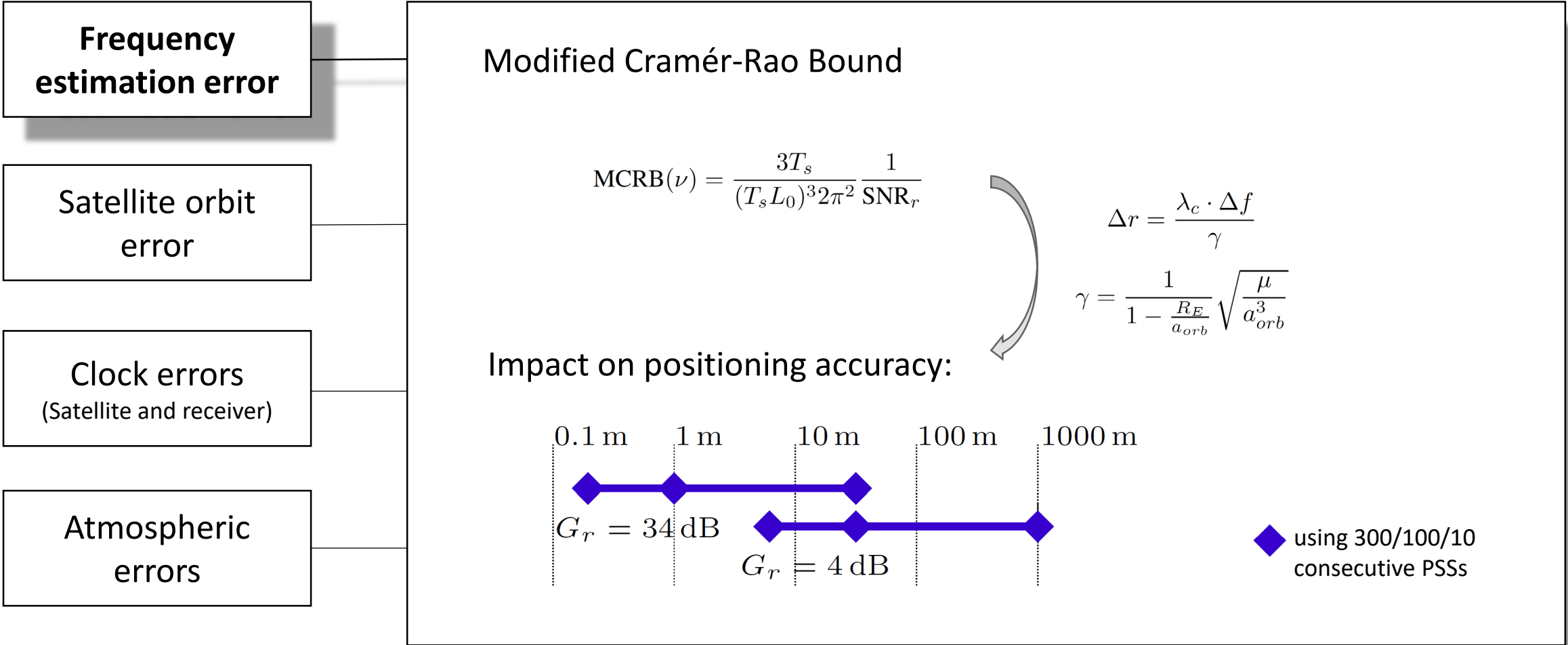
Which sources of error are (most) relevant?

W. Stock, R. T. Schwarz, and A. Knopp, “Error Source Analysis for Doppler Shift Based Opportunistic LEO-PNT With Starlink Signals,” 2025 IEEE/ION Position, Location and Navigation Symposium (PLANS), Salt Lake City, UT, April 2025.



The investigated scenario considers a

- stand-alone
- static
- opportunistic LEO-PNT receiver, performing
- multi-epoch
- Doppler-shift measurements of
- Starlink signals, leveraging
- consecutive Primary Synchronization Sequences (PSS).



Frequency  
estimation error

Satellite orbit  
error

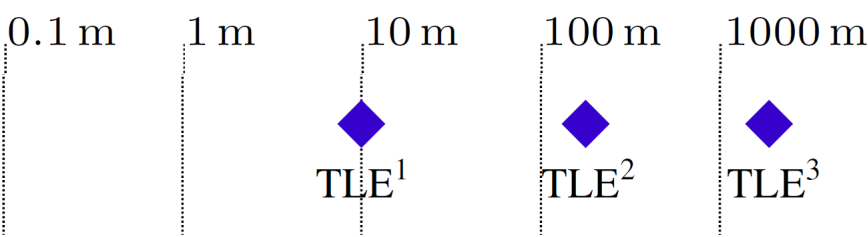
Clock errors  
(Satellite and receiver)

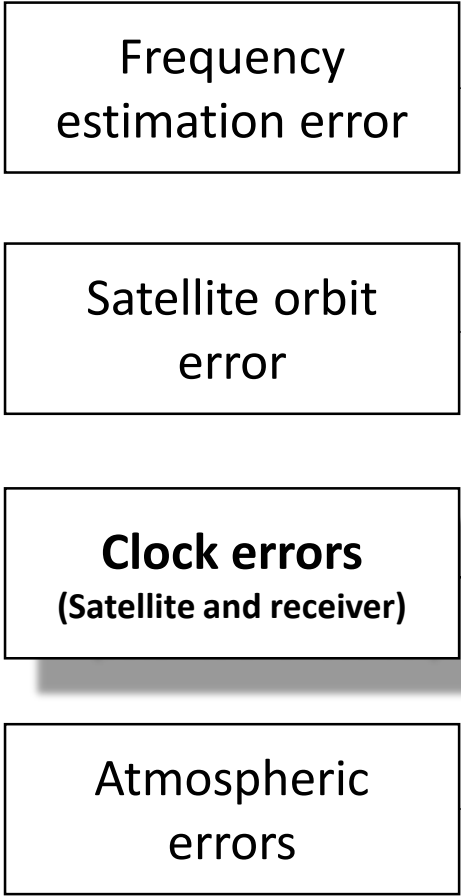
Atmospheric  
errors

Monte-Carlo-Simulation of a single satellite passover

Scenario	Orbit error		
	along	cross	radial
3 NORAD TLE files	2 km	200 m	200 m
2 adjusted TLE files	200 m	200 m	200 m
1 precise TLE files	10 m	10 m	10 m

Impact on positioning accuracy:





### Short-term clock stability

$$\sigma_{f, clock} = \frac{2\pi}{2.25 \cdot 2\pi T_c} \sigma_y(\tau) \tau f_c$$

relationship for a 3<sup>rd</sup> order PLL

### assumed Allan deviations

Clock	$\sigma_y(\tau)$
TCXO	$1 \cdot 10^{-9} \tau^{-\frac{1}{2}}$
CSAC	$3 \cdot 10^{-10} \tau^{-\frac{1}{2}}$
OCXO	$1 \cdot 10^{-12}$

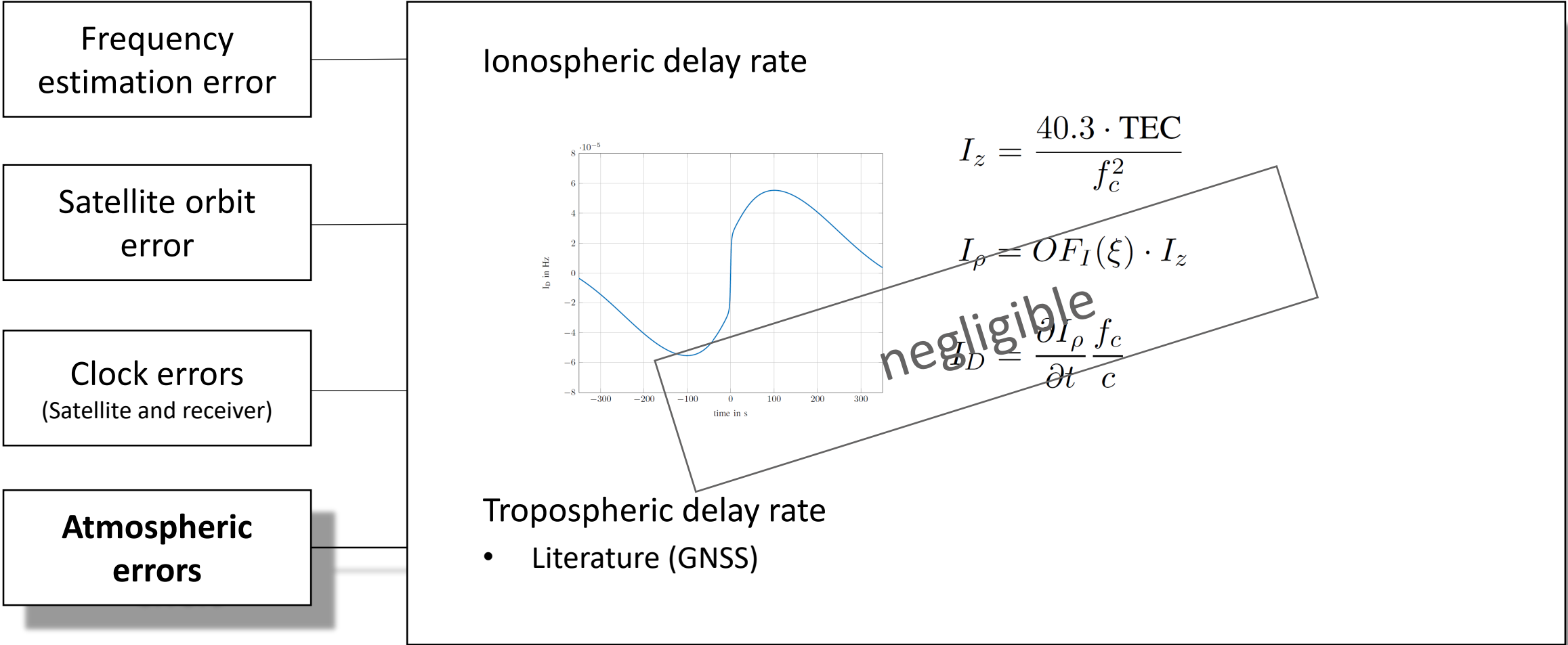
### Impact on positioning accuracy:

0.1 m    1 m    10 m    100 m    1000 m

CSAC

TCXO

◆ using 300/100/10 consecutive PSSs





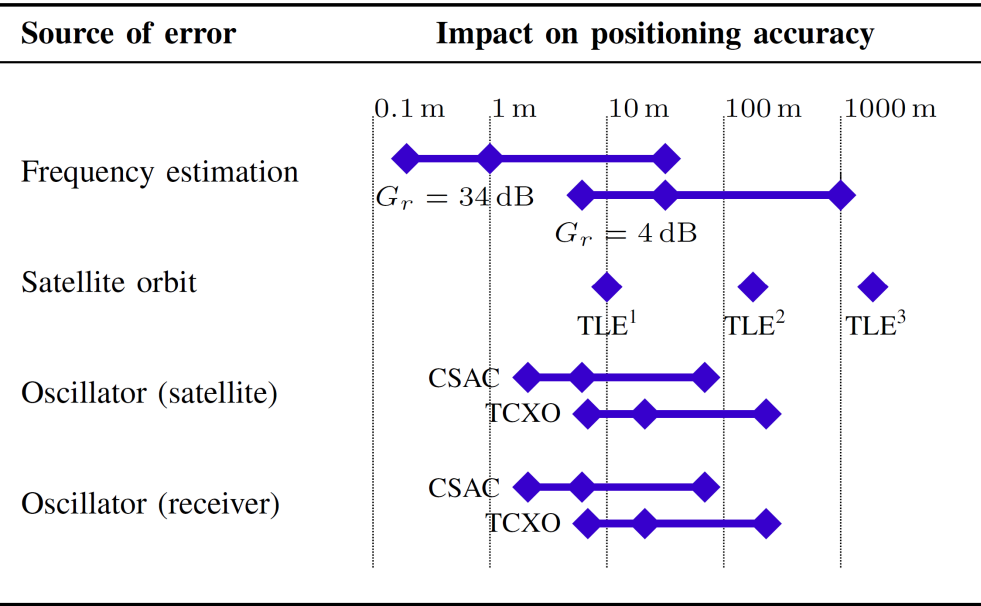
Frequency  
estimation error

Satellite orbit  
error

Clock errors  
(Satellite and receiver)

Atmospheric  
errors

TABLE VI  
IMPACT OF RELEVANT ERROR SOURCES ON THE POSITIONING  
ACCURACY FOR 300/100/10 PSSs / FRAMES USED PER MEASUREMENT

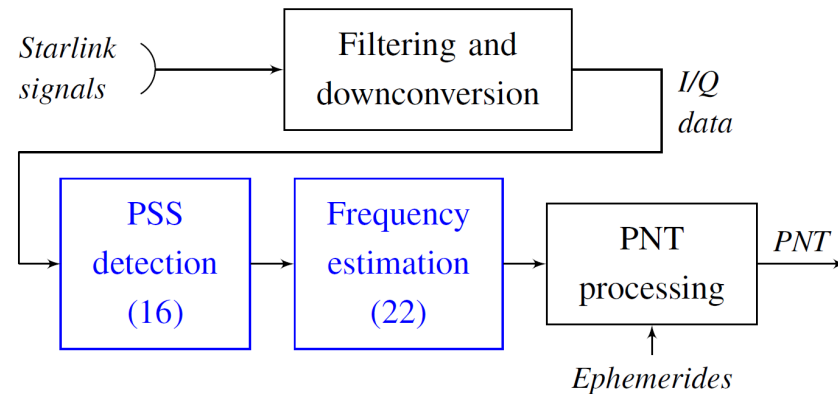


<sup>1</sup> Accurate TLE files  
<sup>2</sup> Adjusted NORAD TLE files  
<sup>3</sup> NORAD TLE files

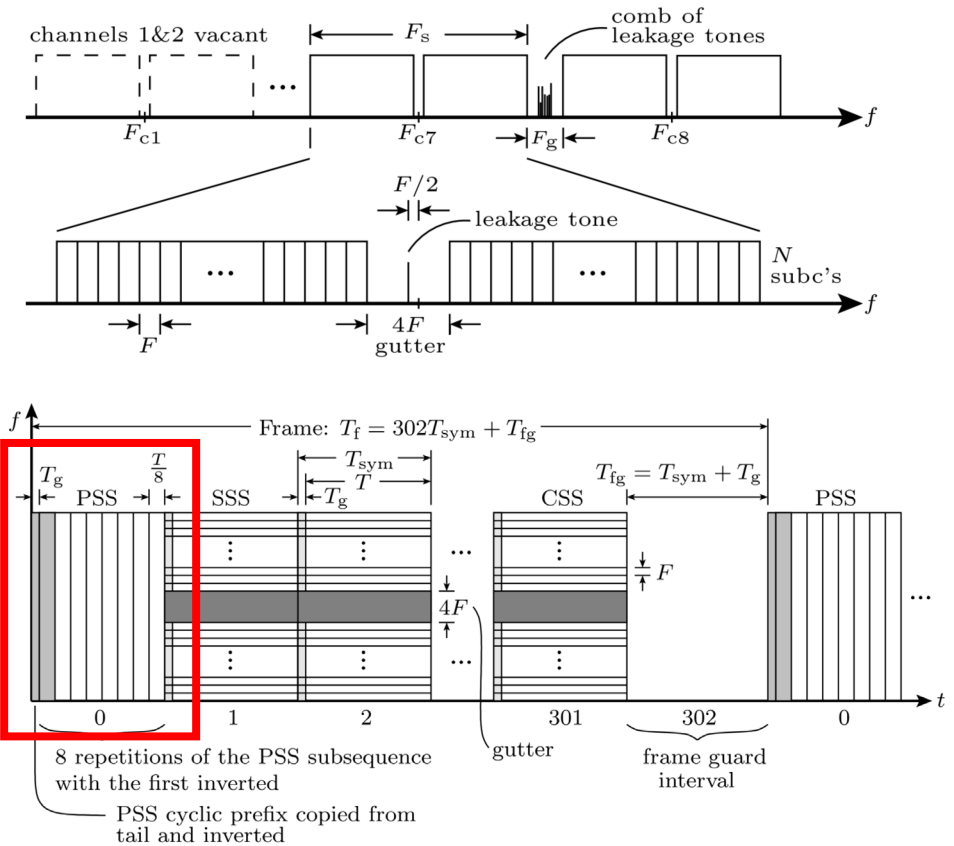
How to estimate the frequency of the signal  
most accurately  
and  
computationally efficient?

W. Stock, C. A. Hofmann and A. Knopp, "Correlation-Based Doppler Shift Estimation for Opportunistic LEO-PNT With Starlink Signals," 2024 IEEE International Conference on Wireless for Space and Extreme Environments (WiSEE), Daytona Beach, FL, USA, Dec. 2024.

- Computationally efficient algorithm
- for Starlink Primary Synchronization Sequence (PSS)
- detection and frequency estimation
- for Doppler-shift based opportunistic LEO-PNT



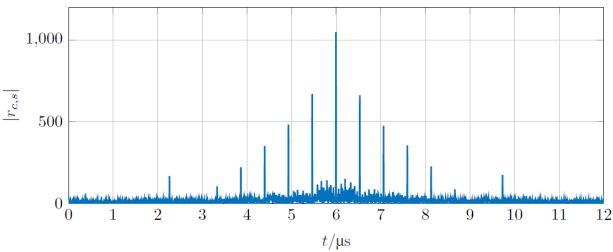
### Starlink Primary Synchronization Sequence (PSS)



T. E. Humphreys, P. A. Iannucci, Z. M. Komodromos and A. M. Graff, "Signal Structure of the Starlink Ku-Band Downlink," in IEEE Transactions on Aerospace and Electronic Systems, vol. 59, no. 5, pp. 6016-6030, Oct. 2023, doi: 10.1109/TAES.2023.3268610.

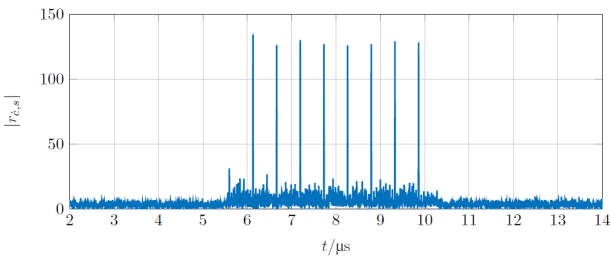
### correlation with PSS

$$r_{c,s}[l] = \sum_{n=0}^{L_c} c[n]s^*[n-l]$$

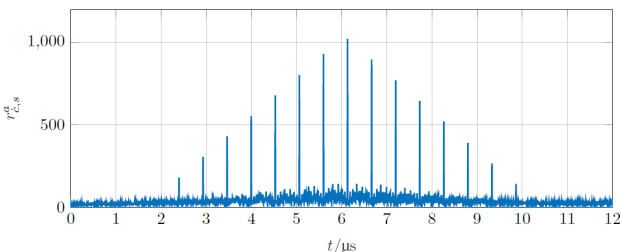


### correlation with subsequence of PSS

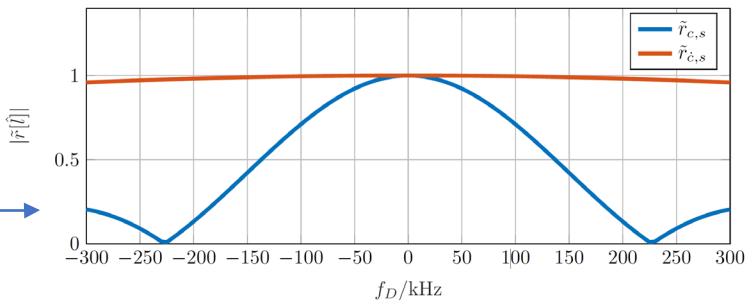
$$r_{\dot{c},s}[l] = \sum_{n=0}^{L_{\dot{c}}} \dot{c}[n]s^*[n-l]$$



$$r_{\dot{c},s}^a[l] = \sum_{i=0}^7 \left| r_{\dot{c},s}[l - iL_{\dot{c}}] \right|$$



### correlation peak for unknown Doppler shift



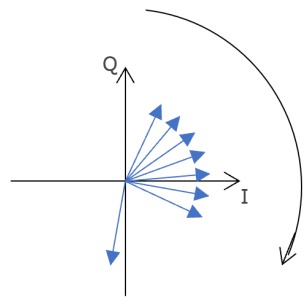
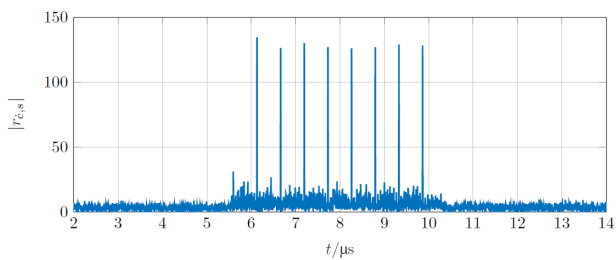
Higher correlation gain

vs.

resilience to Doppler shift misalignment

correlation with  
subsequence of PSS

$$r_{\dot{c},s}[l] = \sum_{n=0}^{L_{\dot{c}}} \dot{c}[n] s^*[n-l]$$



Doppler shift causes  
rotating phase of  
correlation peaks

algorithm

8 correlation peaks

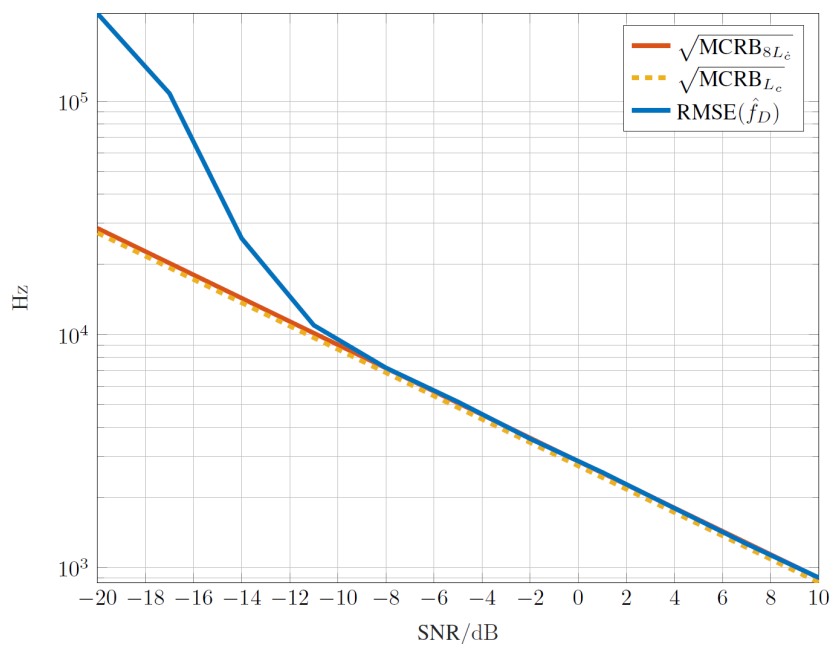
Phase of subsequences  
as transmitted

$$z[k] = y[k] \cdot d^*[k]$$

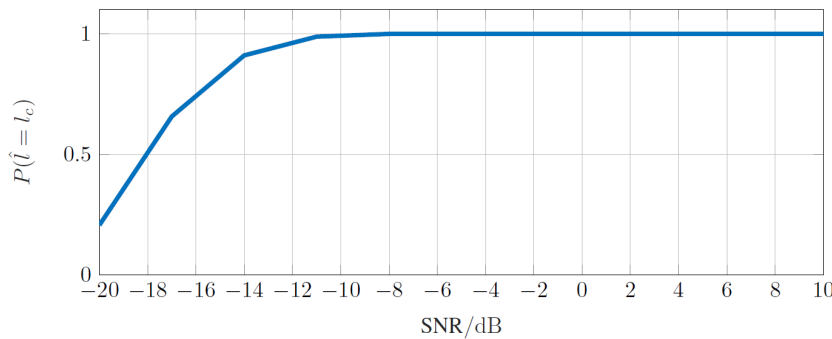
$$R[m] = \frac{1}{L_0 - m} \sum_{k=m}^{L_0-1} z[k] \cdot z^*[k-m]$$

with  $1 \leq m \leq L_0 - 1$

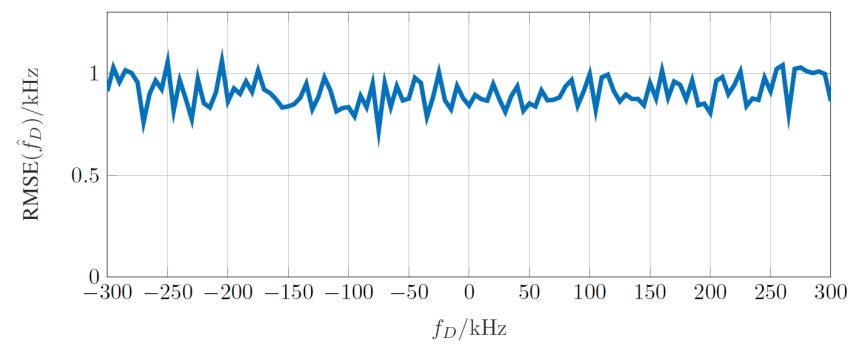
$$\hat{f}_D = \frac{1}{5\pi T_s L_{\dot{c}}} \arg \left\{ \sum_{m=1}^4 R[m] \right\}$$



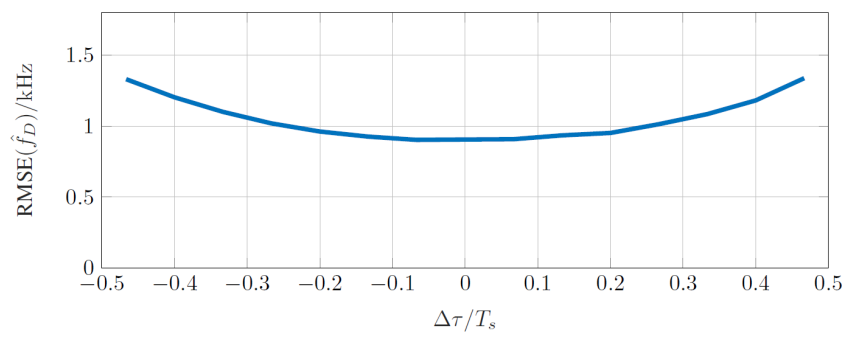
RMSE( $\hat{f}_D$ ) of the Doppler shift estimation for different SNRs



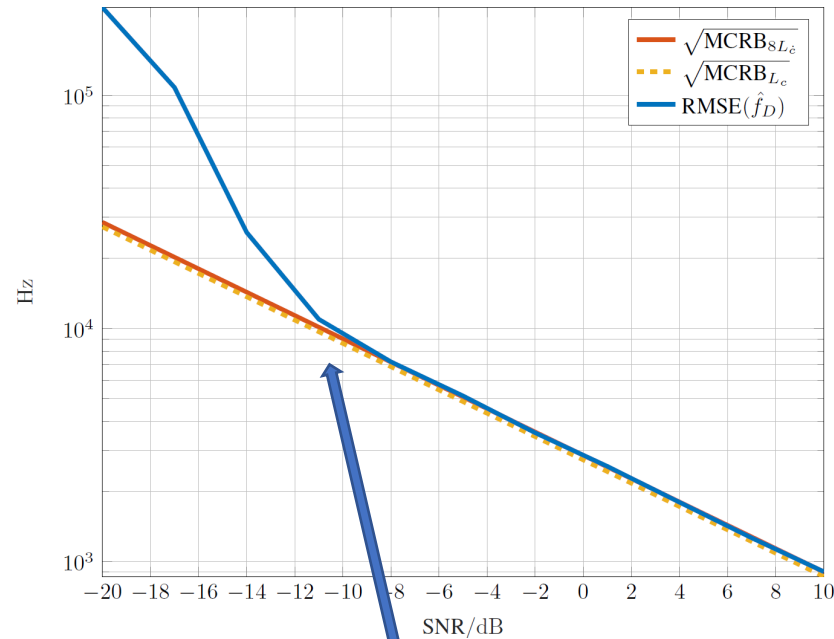
Probability that the PSS is detected correctly



RMSE( $\hat{f}_D$ ) for different Doppler shifts  $f_D$  and SNR = 10 dB



RMSE( $\hat{f}_D$ ) for different sample timing offsets  $\Delta\tau$  and SNR = 10 dB



RMSE( $\hat{f}_D$ ) of the Doppler shift estimation for different SNRs

$$\text{SNR}_T = -11 \text{ dB}$$

- Algorithm works efficiently for  
 $\text{SNR}_T \geq -11 \text{ dB}$
- SNR with isotropic radiator as receiver antenna  
 $\text{SNR}_R = -20.9 \text{ dB}$
- Margin  $M$
- Required receiver antenna gain

$$G_R = \text{SNR}_T + M - \text{SNR}_R$$

$$\rightarrow G_R \geq 10 \text{ dBi for } M = 0 \text{ dB}$$

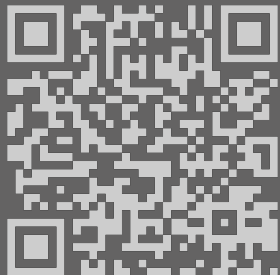
# Thank you!



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Technologieforschung der Bundeswehr



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NextGenerationEU



W. Stock, R. T. Schwarz, C. A. Hofmann and A. Knopp, "**Survey On Opportunistic PNT With Signals From LEO Communication Satellites**," in IEEE Communications Surveys & Tutorials



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